



Performance of Assisted Partial Timing Support (APTS)

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Introduction



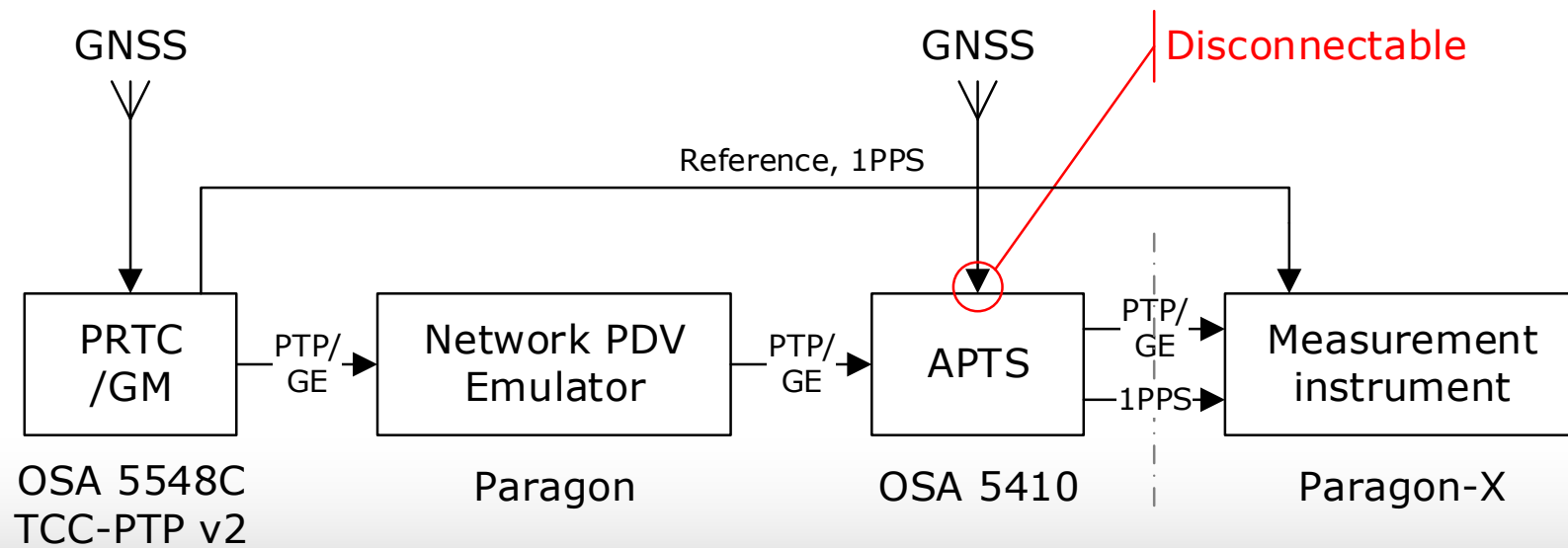
Objectives of the tests:

- Study performance potential of APTS
- Compare several ways of locking to the back-up GM
- Draw conclusions for the architecture

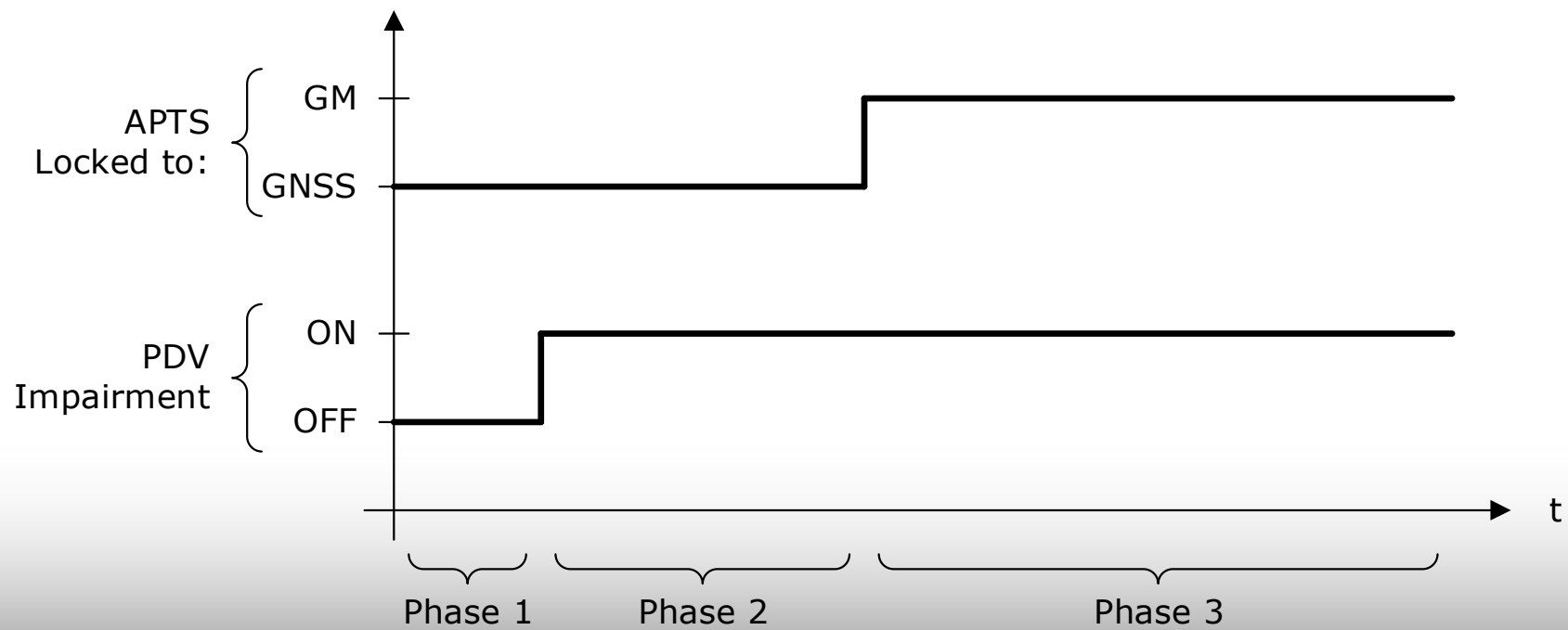
Method

- Emulate PDV of the network
- Measure TE at output of the APTS Clock before and after protection event (GNSS failure)

Test setup



Test sequence



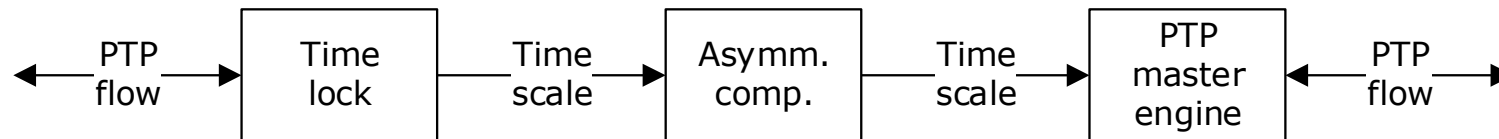
Two APTS mechanisms



1. Normal condition: locked to GNSS

Simultaneously: slave port time-locked to Core GM and measurement of delay asymmetry

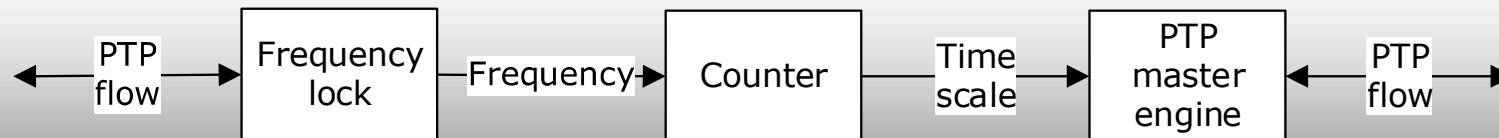
Failure condition: time-lock to Core GM and delay asymmetry compensation



2. Normal condition: locked to GNSS

Simultaneously: slave port frequency-locked to Core GM

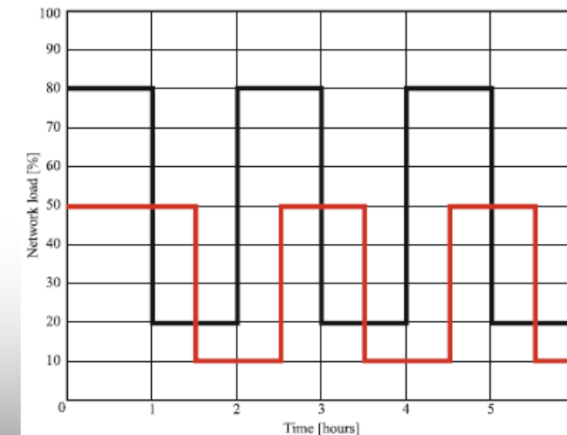
Failure condition: frequency-lock to Core GM; time clock continues ticking with this frequency



Three PDV impairment cases



1. A static delay asymmetry between forward and reverse directions of 10 μ s
2. G.8261/VI test case 12, traffic model 1¹:
80% traffic load in forward direction over 10 nodes
20% traffic load in reverse direction over 10 nodes
3. G.8261/VI test case 13, traffic model 1¹:
Sudden load changes
Black: forward direction (10 nodes)
Red: reverse direction (10 nodes)



Note 1: using Calnex reference PDV traces

Summary of test cases



Test #	APTS mode	PDV impairment profile
1	Lock time via PTP transfer, asymmetry compensation	10 μ s static delay asymmetry
2	Idem	G.8261/VI test case 12, traffic model 1 ¹
3	Idem	G.8261/VI test case 13, traffic model 1 ¹
5	Hold time via PTP frequency transfer	10 μ s static delay asymmetry
6	Idem	G.8261/VI test case 12, traffic model 1 ¹
7	Idem	G.8261/VI test case 13, traffic model 1 ¹

Measurements



What is being measured?

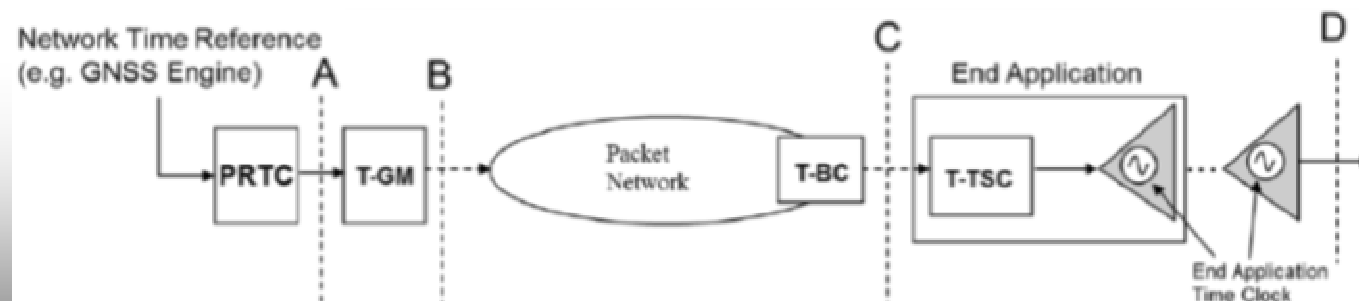
- Time Error TE of the outgoing two-way PTP stream, i.e. $\text{avg}(\text{TE}_{T1}, \text{TE}_{T4})$

What is being calculated?

- $\max |TE|, \text{MTIE}$

What are the results compared against?

- Network Limits @ reference point C, G.8271.1, Amd1, § 7.3



Discussion



- Are the PDV traces emulating G.8261/VI test cases the right ones for evaluating APTS?
- Questionable, because G.8261/VI is for a network without timing support from the network; consequence: the test is actually too tough on the tested APTS function
- Are the Network Limits of G.8271.1 the right ones for evaluating APTS?
- No (formally), because G.8271.1 is for the case of full timing support from the network; G.8271.2 will specify network limits for the case of partial timing support, both assisted and non-assisted; but it is not yet finalized.
- Yes, because: why should the network limit at reference point C be any different in the case of assisted partial timing support?

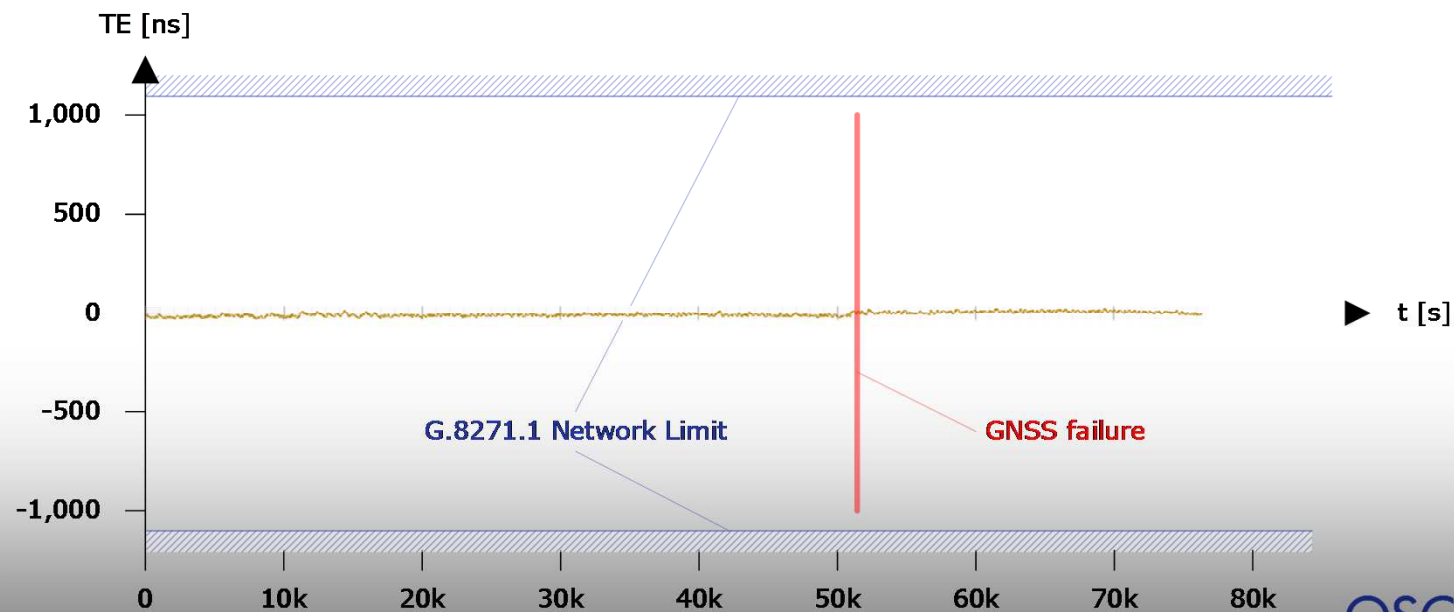
Note 1: Calnex bi-directional reference PDV traces

Test #1, Time Error



Static asymmetry of 10 μ s, APTS = phase lock & asymmetry compensation

$$\max |TE| = \mathbf{38\ ns} \leq 1100\ ns$$

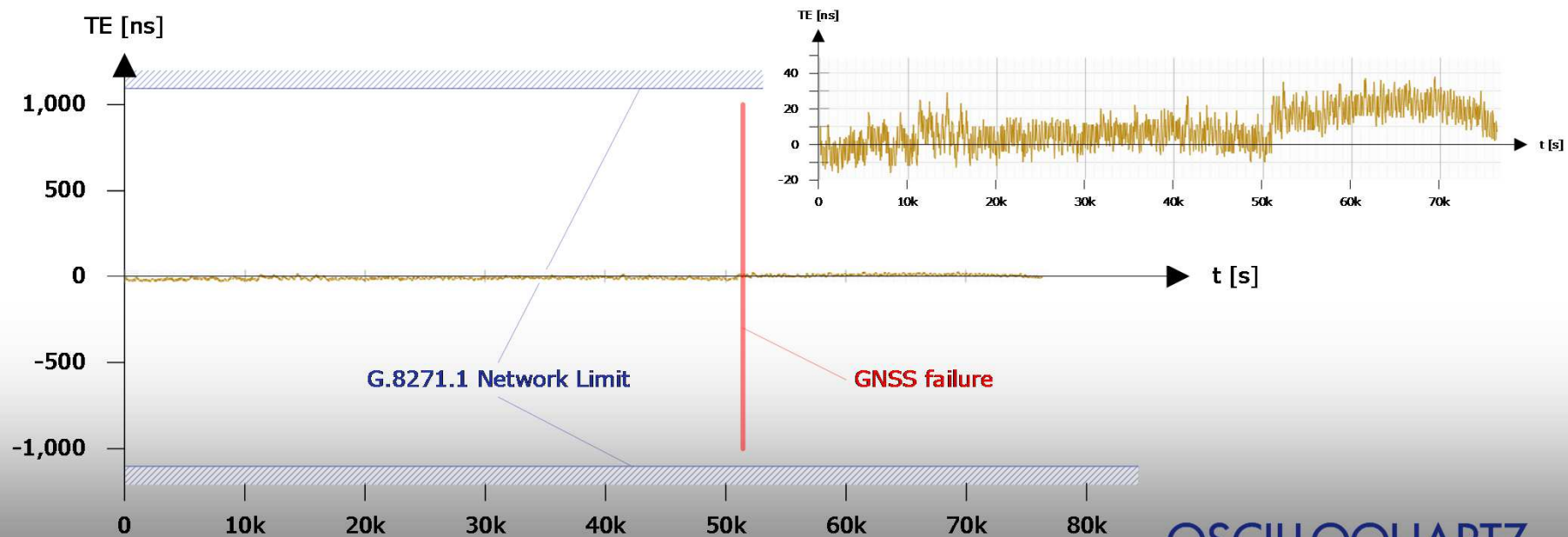


Test #1, Time Error



Static asymmetry of 10 μ s, APTS = phase lock & asymmetry compensation

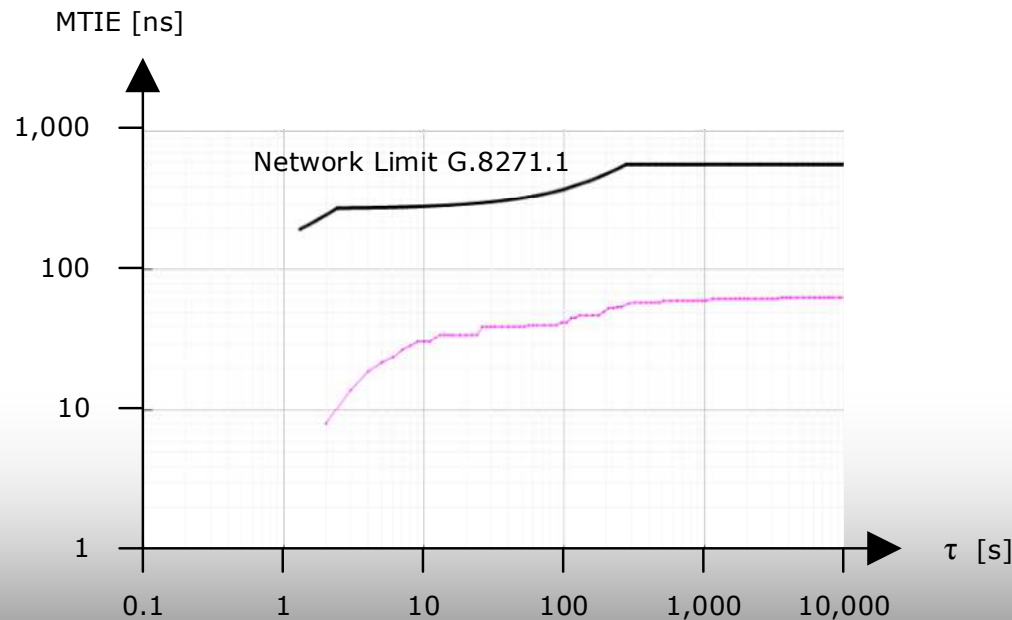
$$\max |TE| = \mathbf{38\ ns} \leq 1100\ ns$$



Test #1, MTIE (dynamic Time Error)



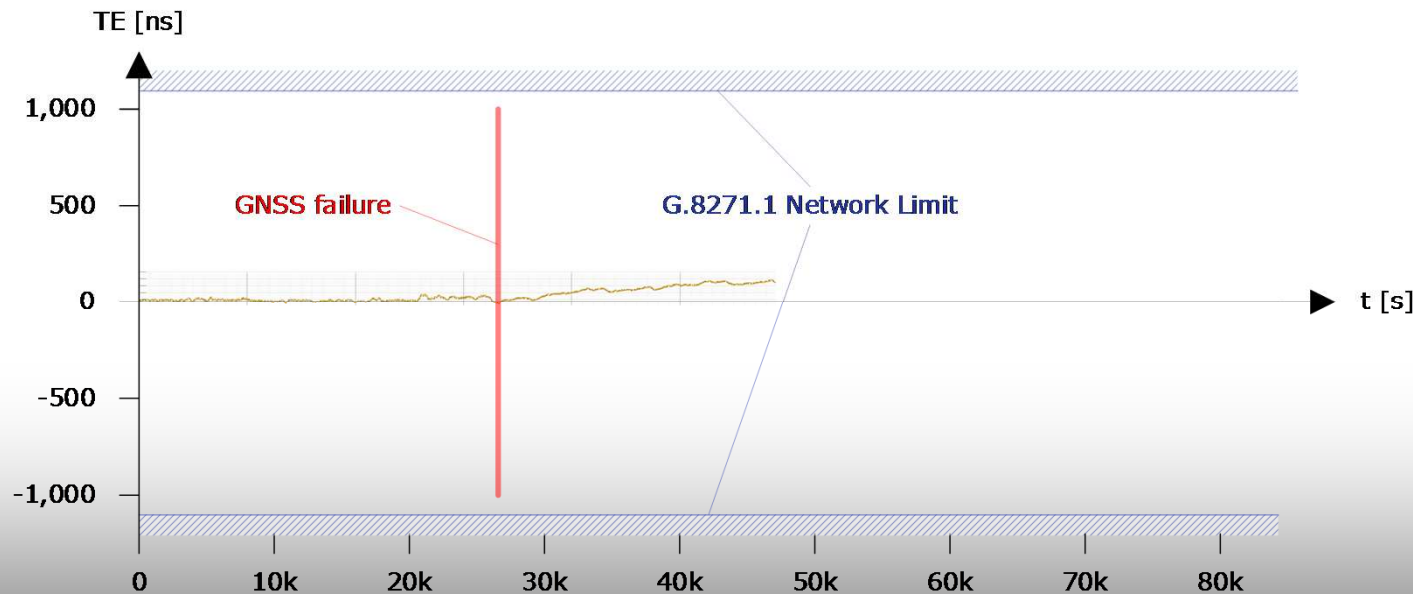
Static asymmetry of 10 μ s, APTS = phase lock & asymmetry compensation



Test #2, Time Error



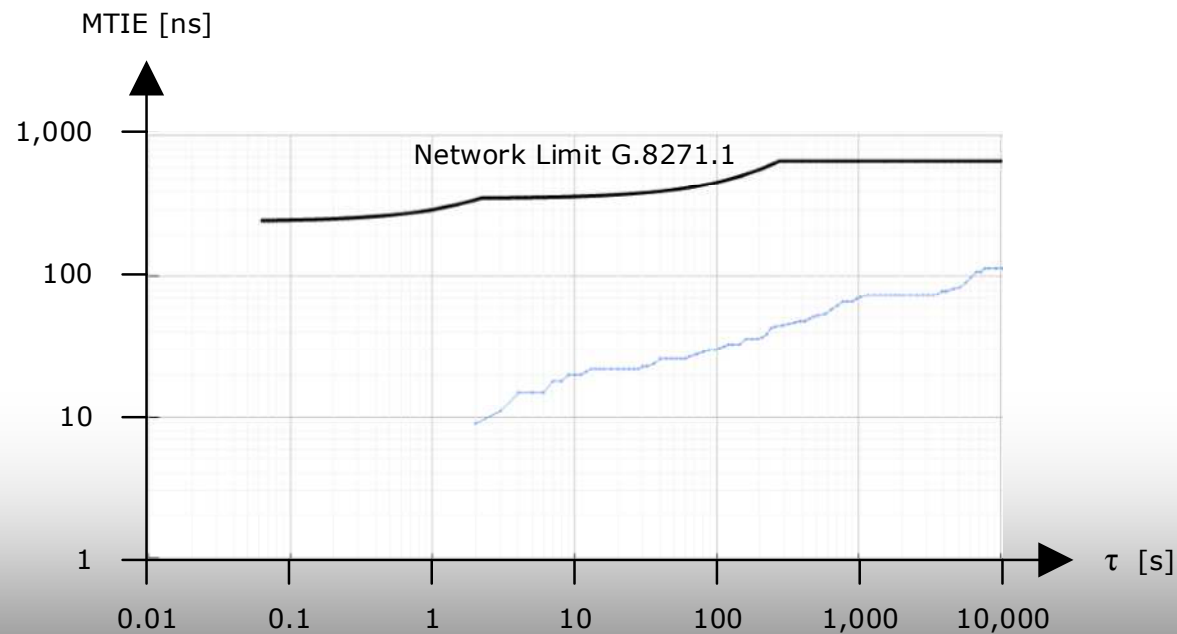
G.8261/VI test case 12-1, APTS = phase lock & asymmetry compensation
 $\max |TE| = \mathbf{116\ ns} \leq 1100\ ns$



Test #2, MTIE (dynamic Time Error)



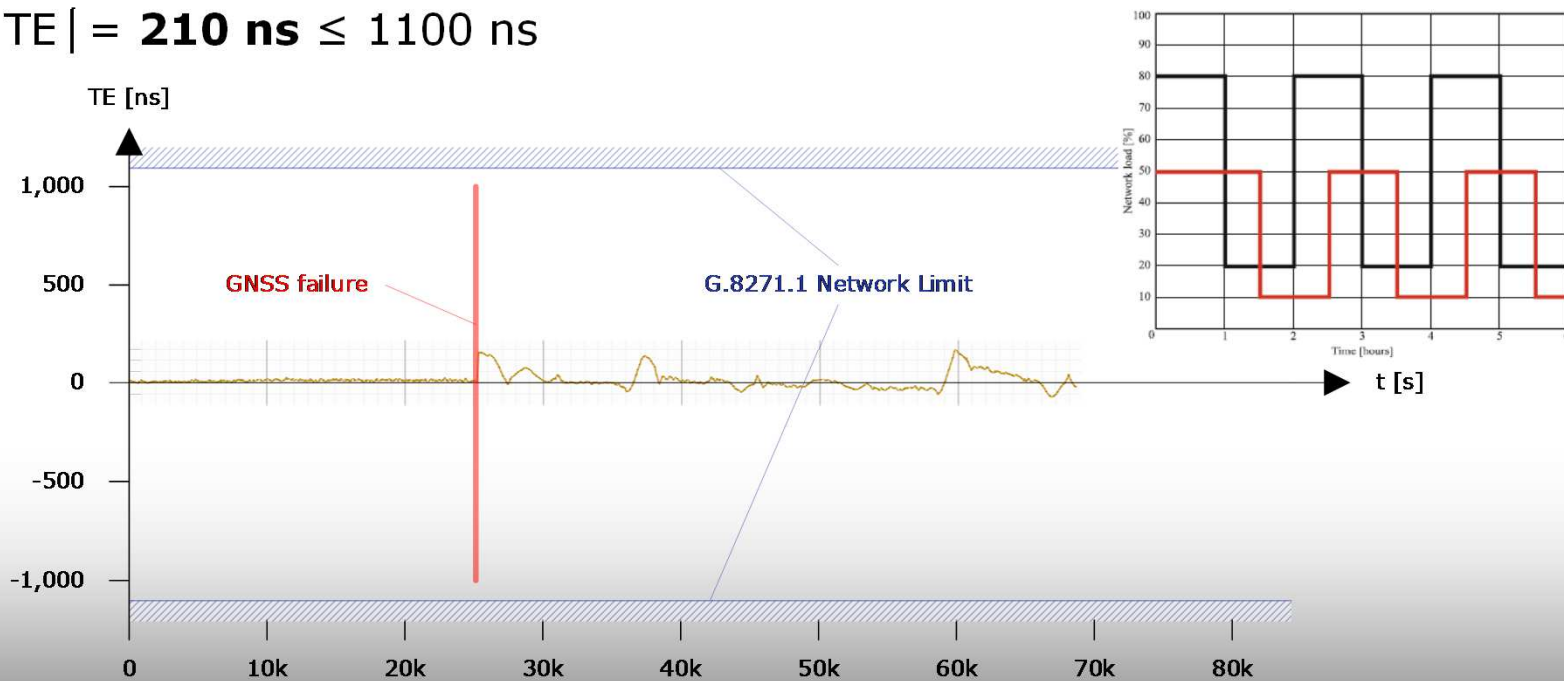
G.8261/VI test case 12-1, APTS = phase lock & asymmetry compensation



Test #3, Time Error



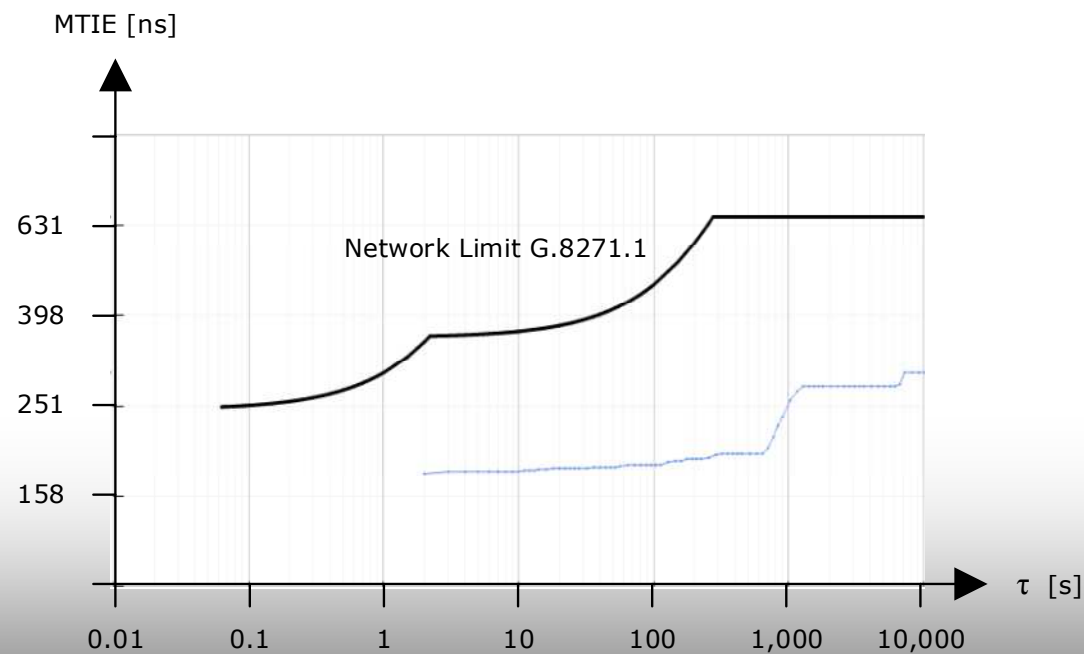
G.8261/VI test case 13-1, APTS = phase lock & asymmetry compensation
 $\max |TE| = \mathbf{210\ ns} \leq 1100\ ns$



Test #3, MTIE (dynamic Time Error)



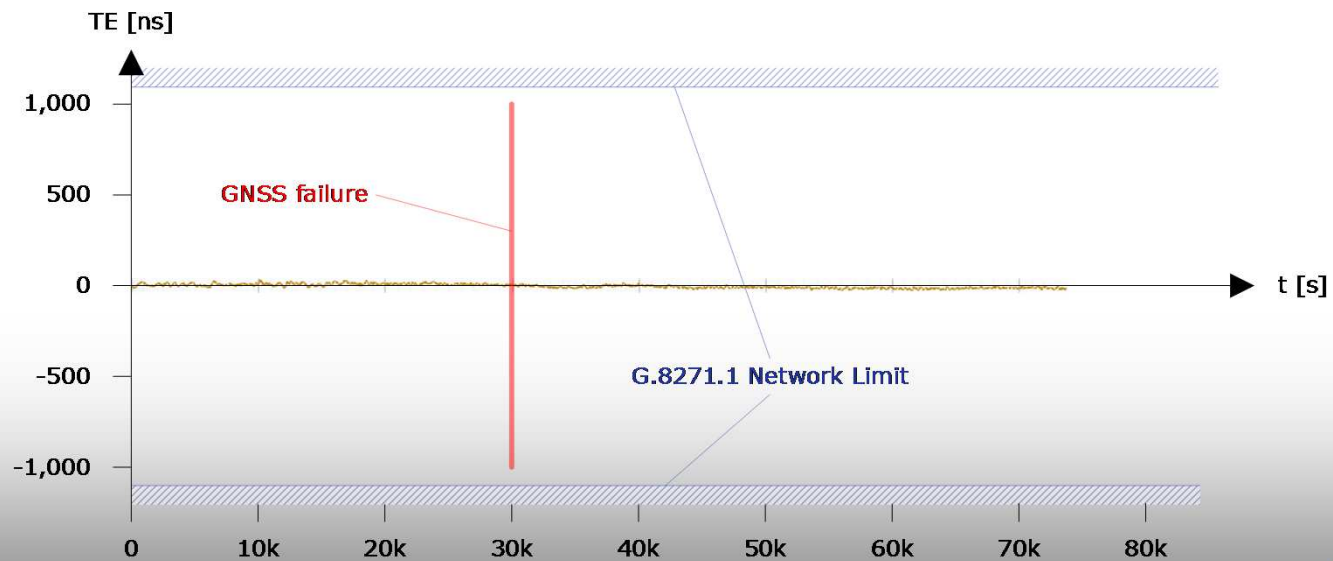
G.8261/VI test case 13-1, APTS = phase lock & asymmetry compensation



Test #4, Time Error



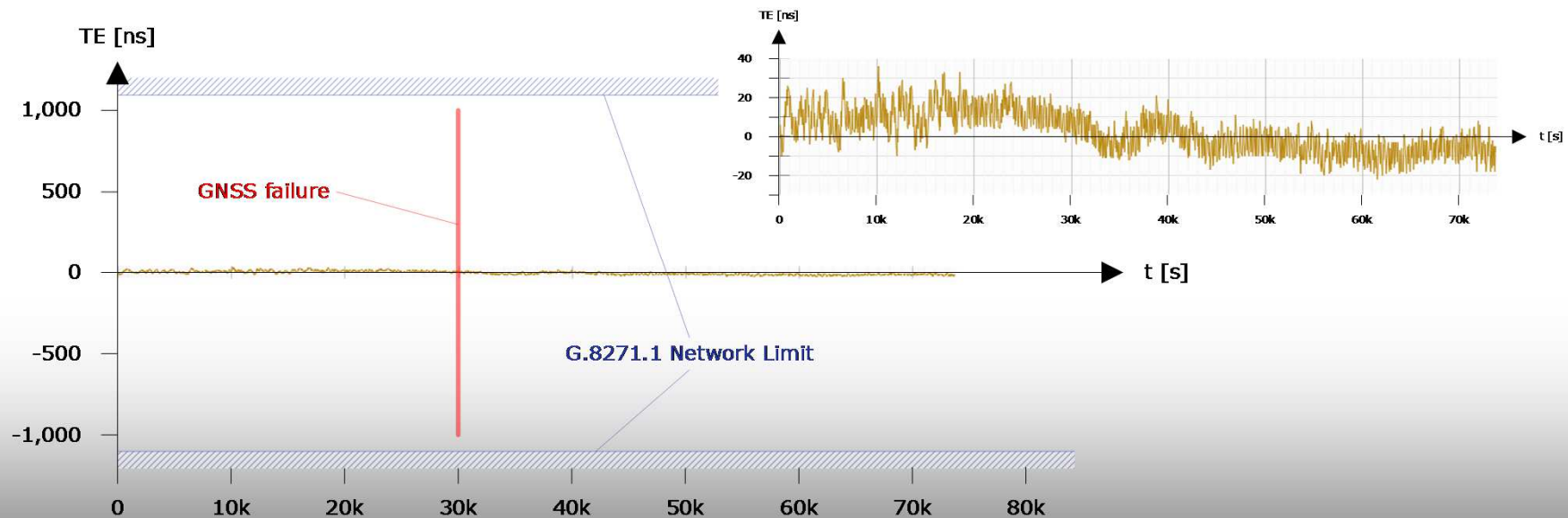
Static asymmetry of 10 μ s, APTS = frequency lock
 $\max |TE| = \mathbf{36\ ns} \leq 1100\ ns$



Test #4, Time Error



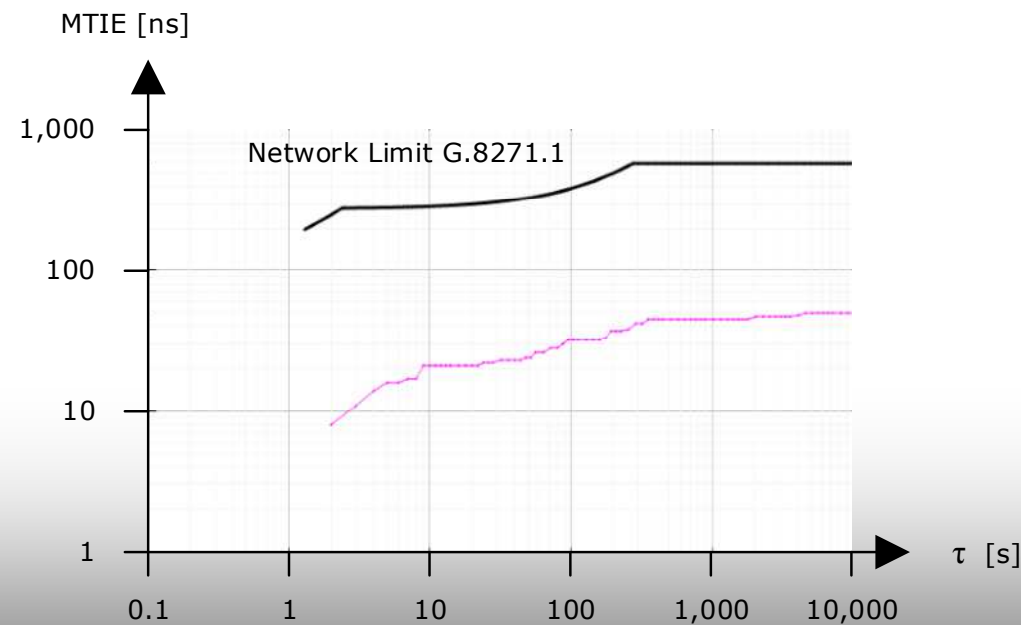
Static asymmetry of 10 μs , APTS = frequency lock
 $\max |TE| = \mathbf{36\text{ ns}} \leq 1100\text{ ns}$



Test #4, MTIE (dynamic Time Error)



Static asymmetry of 10 μ s, APTS = frequency lock

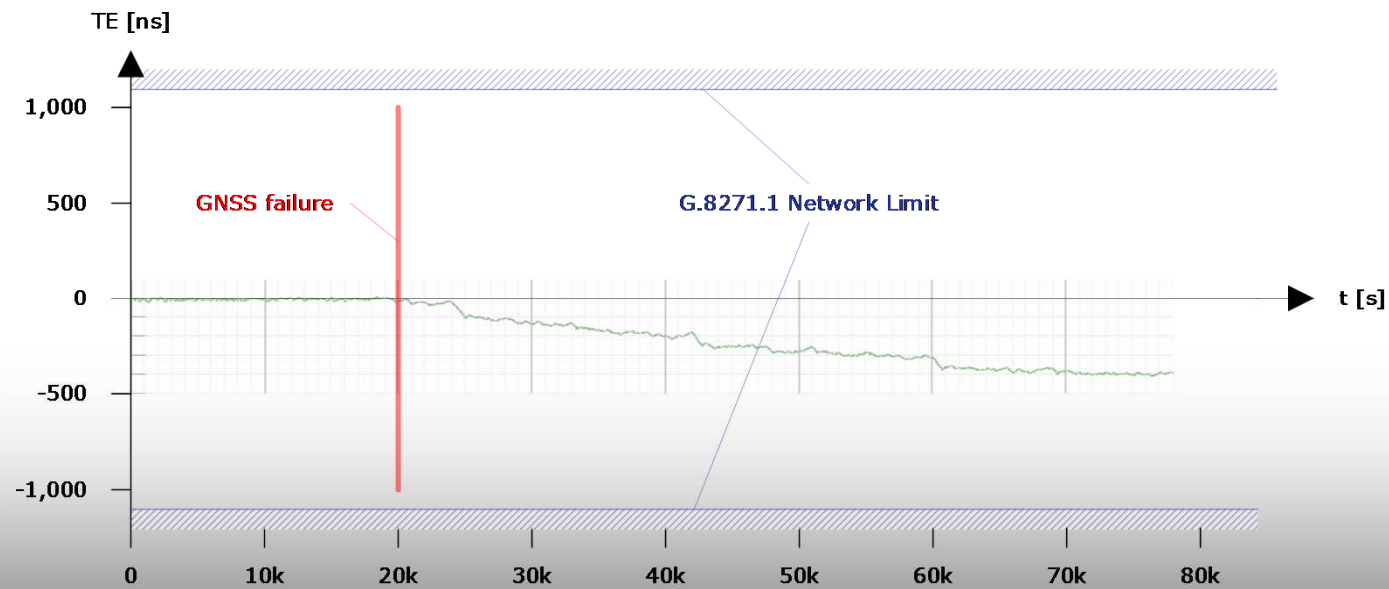


Test #5, Time Error



G.8261/VI test case 12-1, APTS = frequency lock

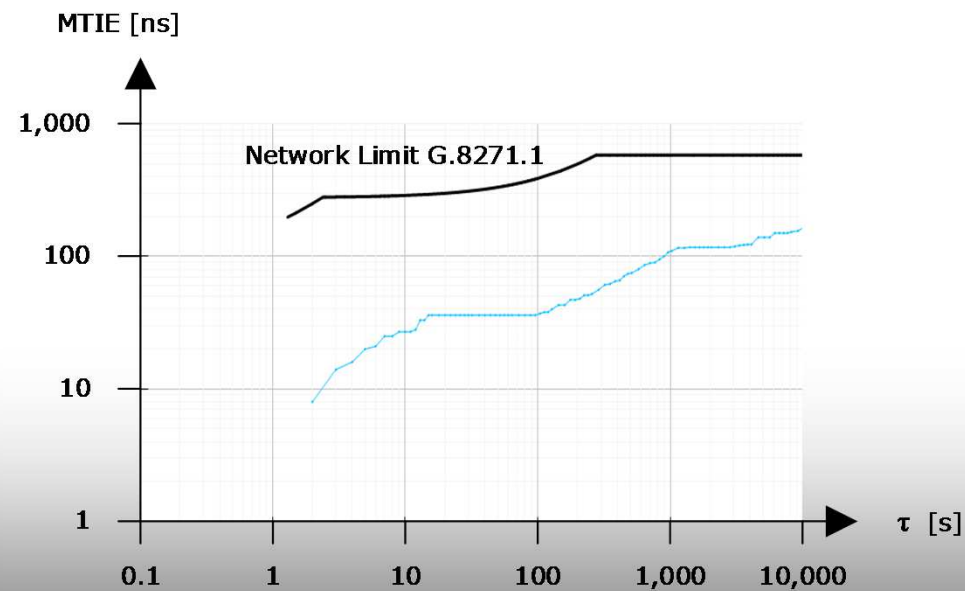
$$\max |TE| = \mathbf{410\ ns} \leq 1100\ ns$$



Test #5, MTIE (dynamic Time Error)

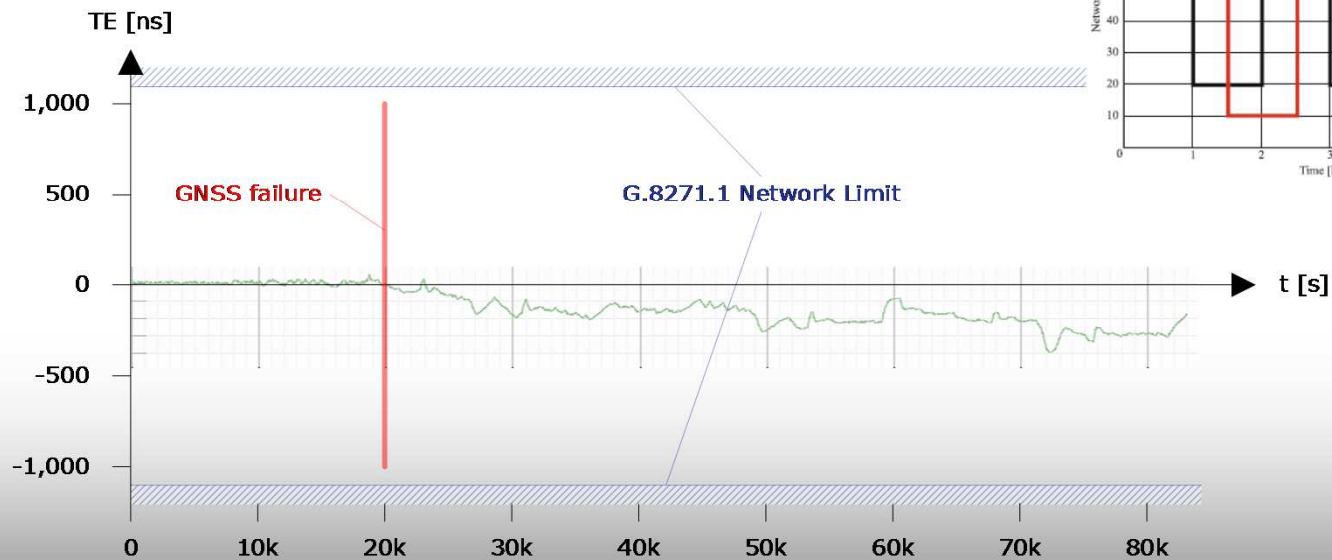


G.8261/VI test case 12-1, APTS = frequency lock



Test #6, Time Error

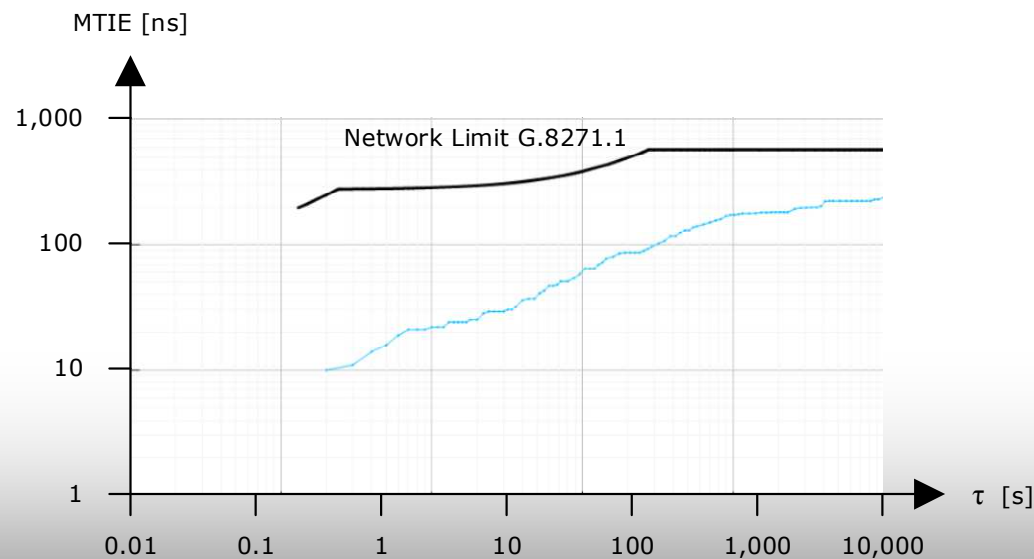
G.8261/VI test case 13-1, APTS = frequency lock
 $\max |TE| = \mathbf{356} \text{ ns} \leq 1100 \text{ ns}$



Test #6, MTIE (dynamic Time Error)



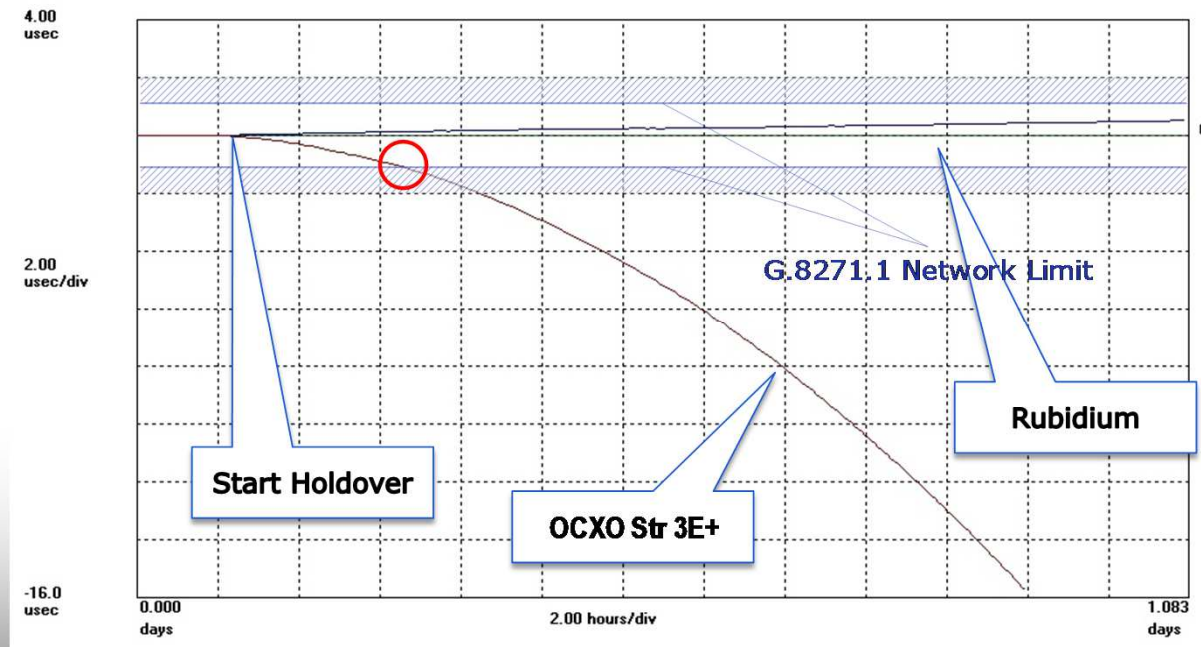
G.8261/VI test case 13-1, APTS = frequency lock



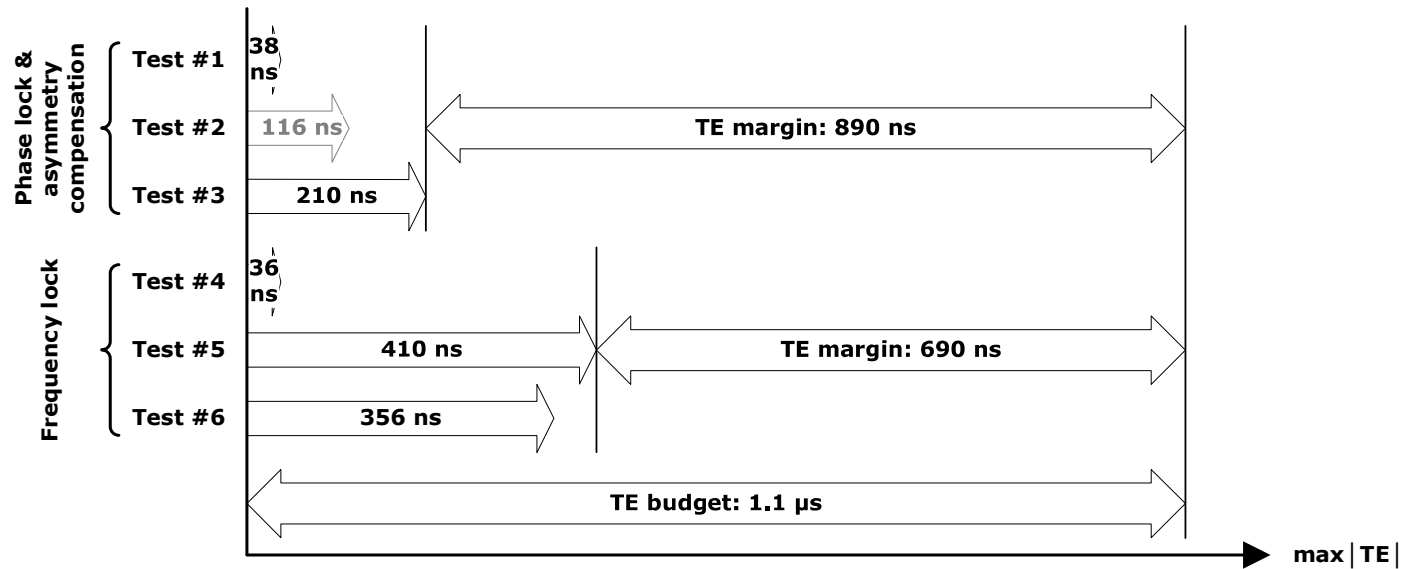
Compared with holdover ...



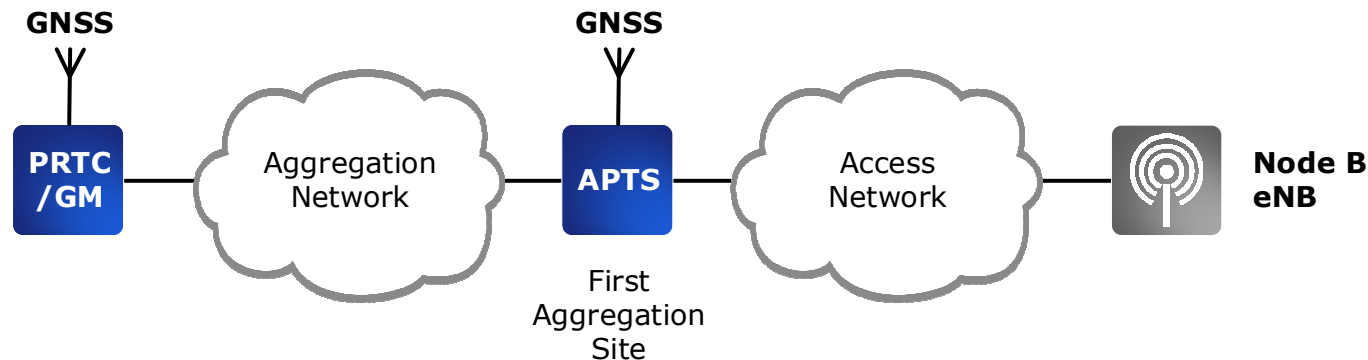
- Holdover (XO & Rb), ideal conditions (temperature, initial offsets):



Summary



Conclusion



- Tests based on G.8261 test cases (!) show that the $\max |TE|$ at the output of the APTS Clock is well below the $1.1 \mu s$ in the GNSS failure case.
- The test results suggest that the APTS Clock can be placed in the first aggregation site.
- With the PDV emulations used, phase lock with asymmetry compensation fares somewhat better than frequency lock, but this probably depends on the test and network conditions.
- The results depend on the algorithms used in the APTS Clock.
- APTS is better than quartz-based holdover.



Thank You



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