



GALILEO-BASED TIMING RECEIVER FOR CRITICAL INFRASTRUCTURES ROBUSTNESS

International Timing and Sync Forum
Brighton (UK)
November 7th, 2019



OUTLINE

1 INTRODUCTION

2 TIMING USER NEEDS

3 GIANO TIMING PLATFORM

4 TIMING SERVICE ROBUSTNESS

5 GIANO CALIBRATION & VALIDATION

PROJECT TEAM /// KEY ROLES

Consortium is composed by companies, institutions and experts with background and competence in timing applications:



Thales Alenia Space in Italy has multi-year experience in GNSS systems and in the development of GNSS-based products for ground and space applications.



Business Integration Partners is involved in the consortium for user groups interface, dissemination activities, providing its experience in strategic analyses and business modelling.



PIKTime Systems is experienced in time-based products and services development and is advisor on precise time, scales and design of time & frequency software algorithms.



Space Research Center of the **Polish Academy of Science** has strong heritage in timing systems, has participated to several European scientific and navigation programmes.



DEIMOS Engenharia a company largely involved in GNSS projects and with deep knowledge and experience in SW and algorithms development for GNSS-based equipment.

GALILEO-BASED TIMING RECEIVER FOR CRITICAL INFRASTRUCTURES ROBUSTNESS



GIANO Project Context

“ A **growing concern** exists regarding the possibility of **jamming** and **spoofing** GNSS signals, with the consequent **disruption of critical services** and infrastructures that rely heavily on GNSS timing to operate ... ”



Project Drivers

1. Fulfillment of specific **T&S needs** for **Critical Infrastructures** (health, safety, economic & social welfare).
2. Provision of **robust timing services** for critical users belonging to **Energy, Telecommunications, Finance** domains.
3. Promotion of **Galileo & EGNOS** use for infrastructures protection, improving GNSS-based timing solutions resilience to RF environmental threats.






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TIMING USER NEEDS /// STAKEHOLDERS POINT OF VIEW



Stakeholders feedbacks revealed a high interest in **accuracy**, **integrity** and **robustness** features:

- ▶ **Accuracy**  **91%** of the interviewees
- ▶ **Integrity**  **64%** of the interviewees
- ▶ **Robustness**  **54%** of the interviewees



Continuity of service & availability features are perceived as **less important**, due to the fact that often redundant systems are used



Security, continuity & availability not perceived among fundamental features

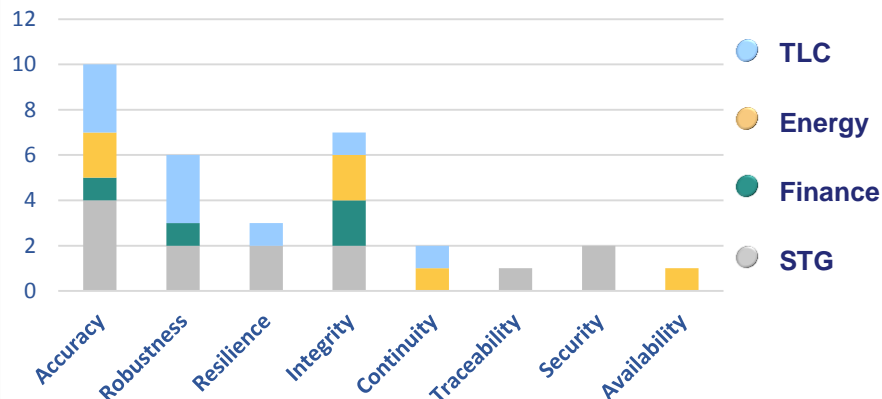


Criticality due to **environmental threats** (jamming, spoofing, ...)

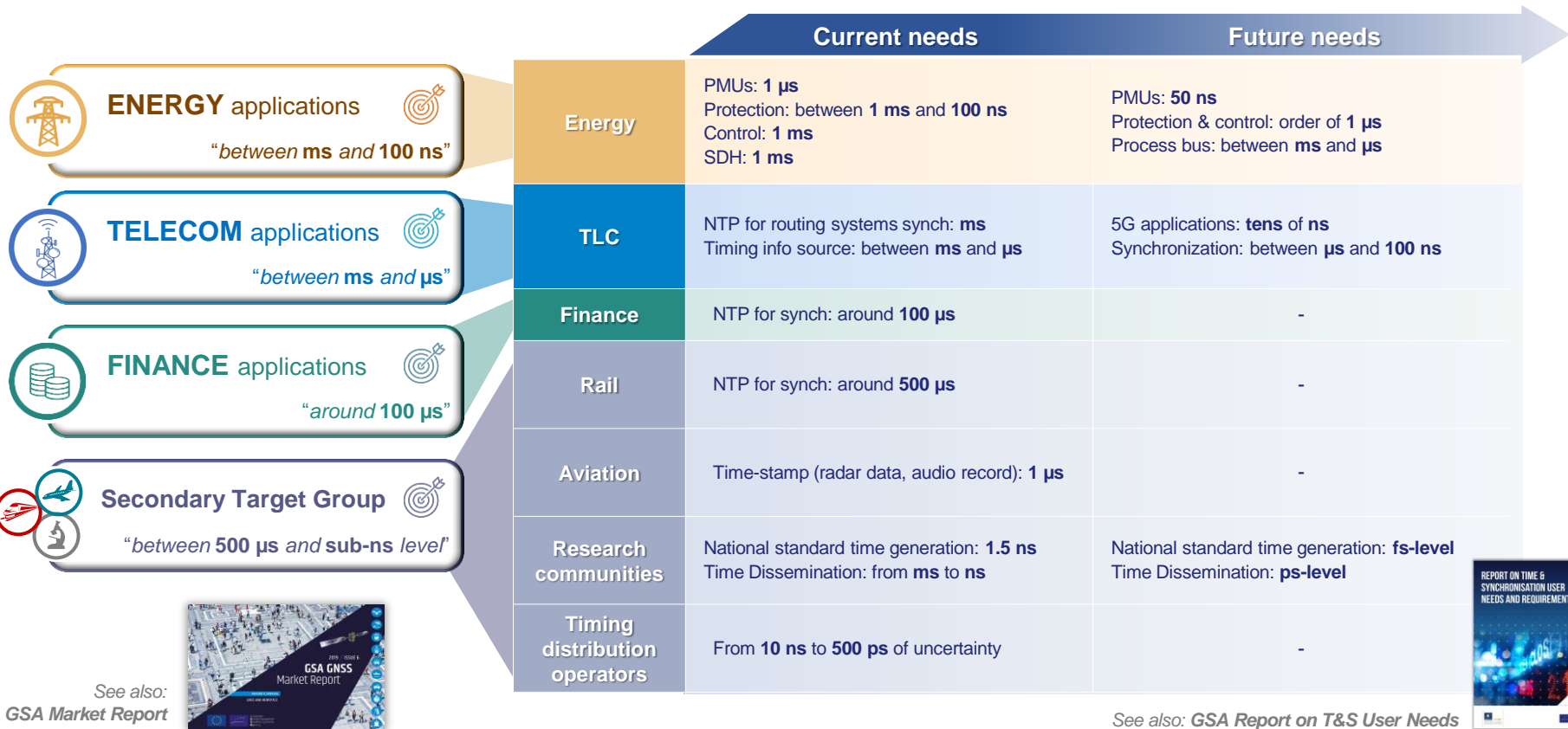


Lack of correlation between security and T&S devices by Stakeholders point of view!

Main Features (pointed out by interviewees)



TIMING USER NEEDS /// SCENARIO EVOLUTION



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GIANO TIMING PLATFORM /// PROTOTYPE OVERVIEW



TIMING RECEIVER

composed by
GNSS Receiver
&
Timing Distribution
Module



COTS ANTENNA

designed to accommodate
L1/E1 & L5/E5 bands



M&C PC

control / monitoring SW
for platform configuration
and evaluation of KPIs



* TRL7 - System Prototype demonstrator in operational environment

2019 - Design & Development

2020 - Integration & Testing

2021 - Final Product

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TIMING SERVICE ROBUSTNESS /// KEY DRIVERS



GNSS Processing

- **Multi-GNSS** and **Combined solution** capability (**GPS**, **Galileo** and **EGNOS**).
- **Flexibility** and **Configurability** from single to multi-frequency (L1/E1, L5/E5a).
- **Tunable bands** with innovative **Direct-Sampling** approach and **Digital Down-Conversion**.
- Synchronization with **GST** or **GPST**.



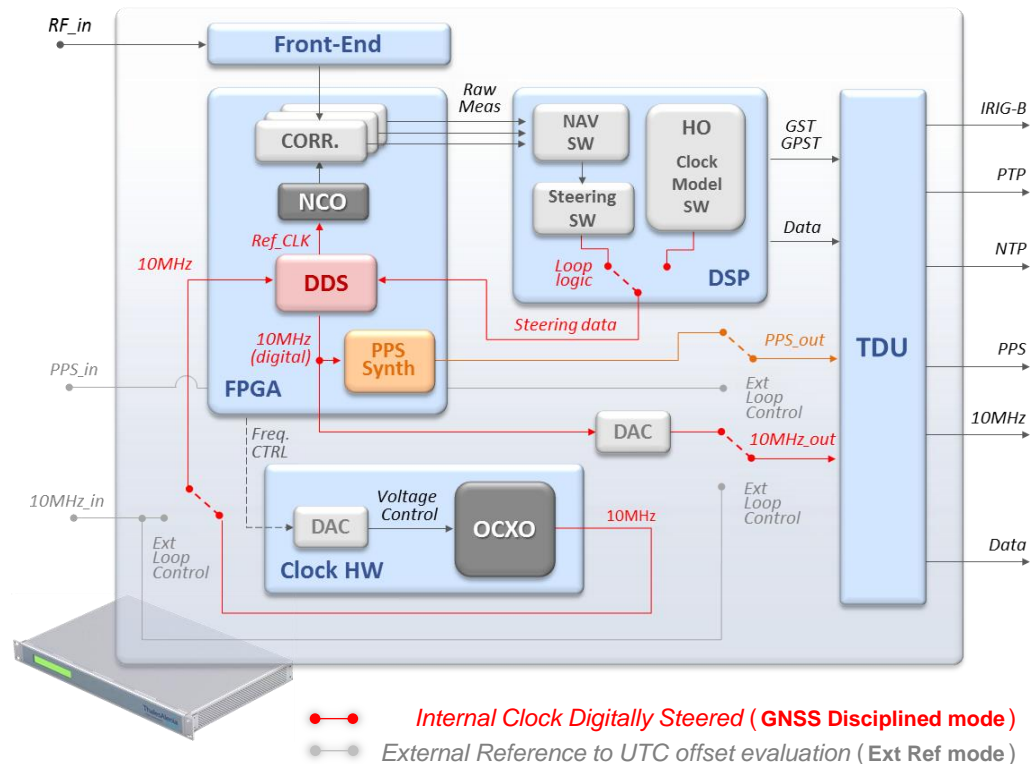
Improved Timing Robustness

- **Jamming & Spoofing** detection / mitigation capabilities.
- Use of **Galileo OS-NMA authentication** service.
- Availability of **EGNOS corrections**.
- **T-RAIM** algorithm for time solution **integrity** (single or multi-constellation based).
- **Accurate Time-Steering** and **Holdover** with transparent output towards user.
- Periodic **Calibration** or **Auto-Calibration** capability.

TIMING SERVICE ROBUSTNESS /// SYNCHRONIZATION

Digital Time-Steering Benefits

1. Improved timing signal **continuity & availability**:
 - No transitory / jumps due to lack of GNSS signals
 - Smooth convergence & synch recovery after holdover
2. Higher level of **configurability** (FW/SW based approach)
3. Solution **independent** from internal **clock** model
4. Early **malfunction** and **anomalies detection**:
 - Easier maintenance (SW based approach)
 - On-demand or continuous integrity monitoring & notification
5. KPIs for **Service Level Agreement monitoring**:
 - Synchronization predictions
 - A-posteriori synchronization evaluation
 - Autonomous time service performance monitoring



TIMING SERVICE ROBUSTNESS /// RF ENVIRONMENT



Interference Detection & Mitigation



Antenna level:

- RHCP Gain Roll-off
- **Front-End** (BPF Bandwidth, LNA, ...)



Pre-correlation level (i.e. in FPGA, based on RFI power before de-spreading):

- **AGC**
- Digital Pulse **B**lanking
- Frequency **E**xcision



Multipath Detection & Mitigation



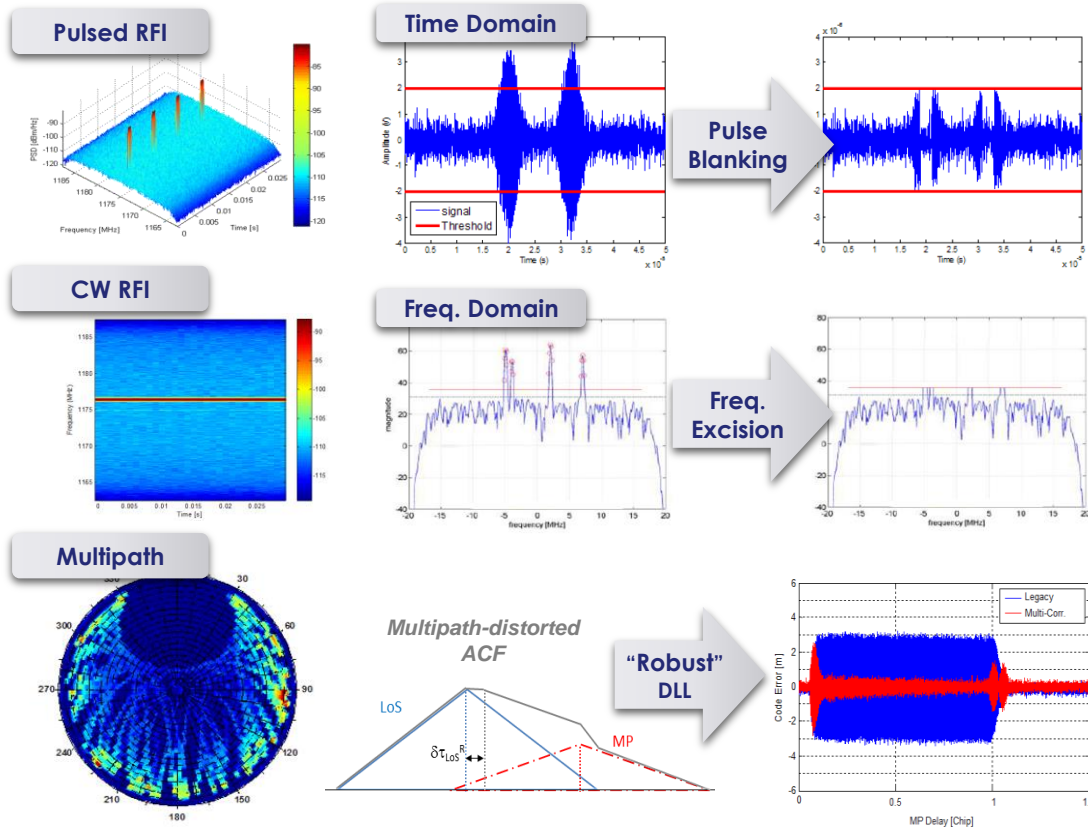
Antenna level:

- RHCP-LHCP **D/U** ratio



Post-Correlation level (i.e. in DSP):

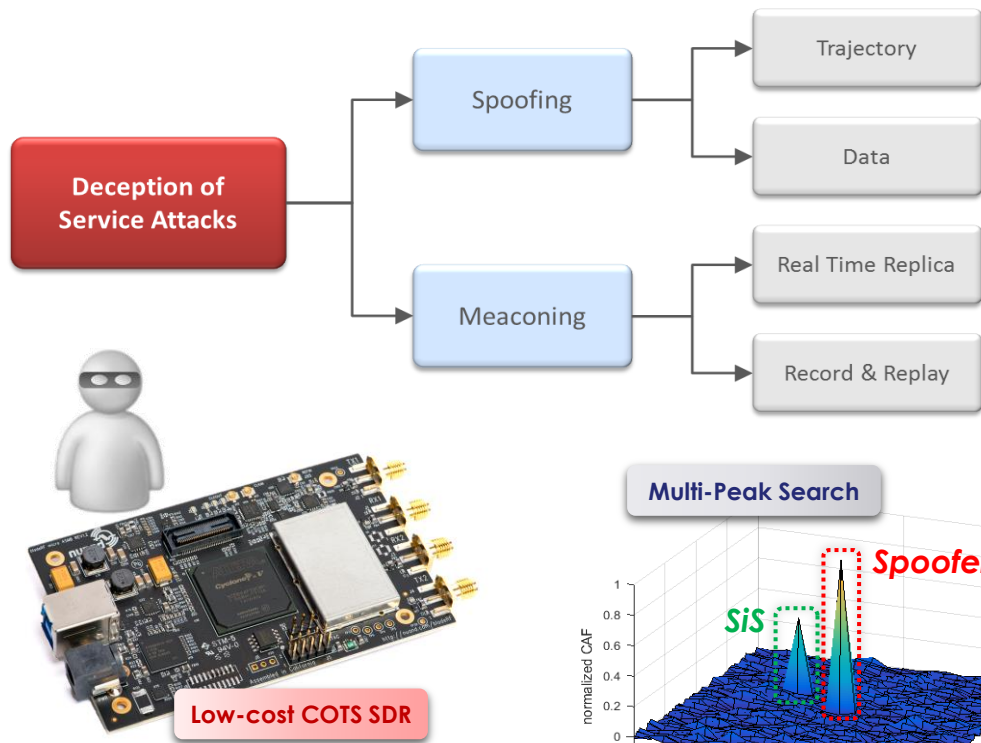
- Multi-Correlator based **DLL** discriminators
- **O**bservables based (C/N0, CMC, etc.)



TIMING SERVICE ROBUSTNESS /// RF ENVIRONMENT

Spoofing Detection & Mitigation

- @ **Pre-correlation level:**
 - AGC Monitoring
- @ **Acquisition / Correlation level:**
 - Multi-Peak Search
 - Centre of Mass & Total Energy
- @ **Tracking / Observables level:**
 - Doppler / code delay rate consistency check
- @ **Navigation level:**
 - Anti-Spoofing RAIM
- @ **External Aiding / System Based level:**
 - Navigation Message Authentication

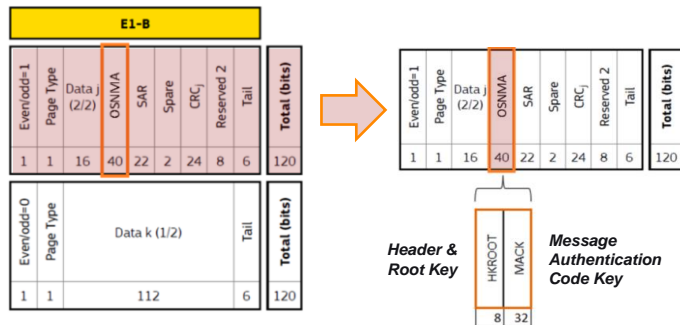


TIMING SERVICE ROBUSTNESS /// AUTHENTICATION

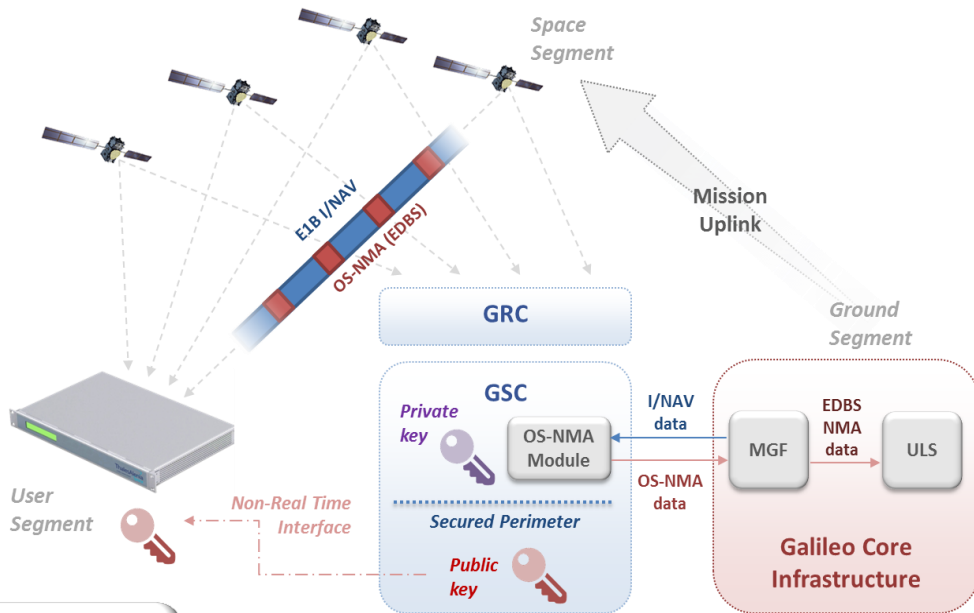


Open Service Navigation Message Authentication (OS-NMA)

- I/NAV Galileo message is broadcasted in E1-B



- OS-NMA is based on **TESLA** protocol (Time Efficient Stream Loss-tolerant Authentication).



Anti-Replay protection based on OSNMA unpredictable symbols!

TIMING SERVICE ROBUSTNESS /// INTEGRITY



T-RAIM Time Solution Integrity Monitoring

For a typical Timing Receiver, the position is **known** and **static**.

Reduced number of unknowns has to be estimated with respect to the full Position Velocity Time (PVT) solution:

- Clock **bias**
- Clock **drift**

Redundancy can be exploited to:

- Increase **timing solution reliability**
- **Detect inconsistencies** among GNSS observables
- **Identify outliers** in measurement set

The **availability of several GNSS constellations** provides a significant opportunity to further **improve T-RAIM** performance:

- **T-RAIM** for **Single-Constellation**
- **T-RAIM** for **Multi-Constellations**

In case of Multi-Constellation T-RAIM, **Inter-System Offsets** (i.e. GGTO) and **Drifts** must be carefully handled.

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GIANO VALIDATION /// CALIBRATION ASPECTS



In-factory **calibrated equipment** is subject to **degradation** and needs to be **periodically re-calibrated**. Degradation is caused mainly by:

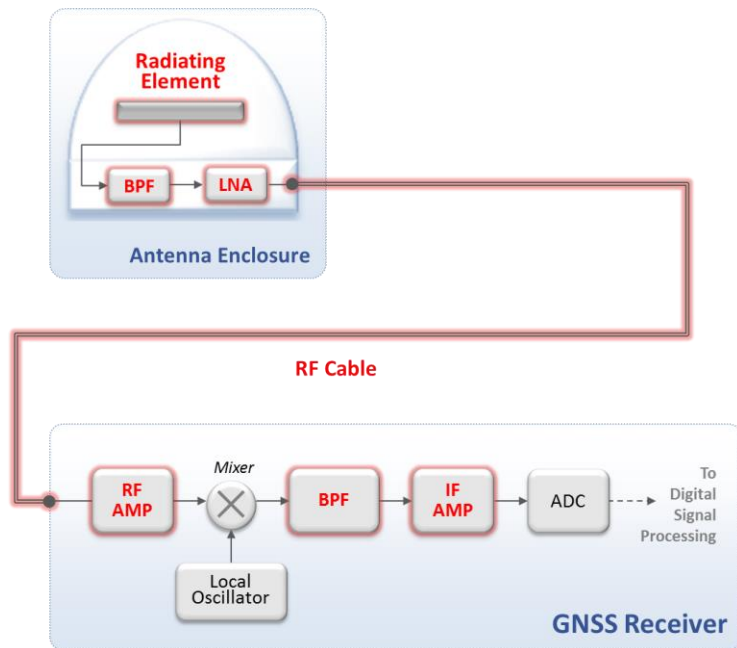
- **Aging** of components (i.e. random changes w.r.t. initial operating points)
- **Retrace** (i.e. steadiness of delay measurements after power-cycles)
- **Operating** conditions (typically different from calibration laboratory ones)

Calibration is typically performed in **two ways**:

1. **Absolute Calibration**: delays are measured against a simulated test signal with identifiable RF timing marker:
 - @ **Antenna level** using a test inject probe antenna
 - **After Radiating Element** prior to filters and LNA
2. **Relative Calibration**: delays are measured against a reference receiver that has been previously calibrated.



A built-in **Auto-Calibration Technique** will be studied and its feasibility in a commercial product will be investigated for industrialization phase.



** Items in red introduce a substantial delay*

GIANO VALIDATION /// TEST STRATEGY



Timing platform will be tested through an **extensive validation test campaign**, conducted in **four phases**, through specific involvement of Team's experts and support of European laboratories:



1.

TAS-I premises (Italy): verification of GIANO **interfaces**, **functionalities** and platform **integration**.

2.

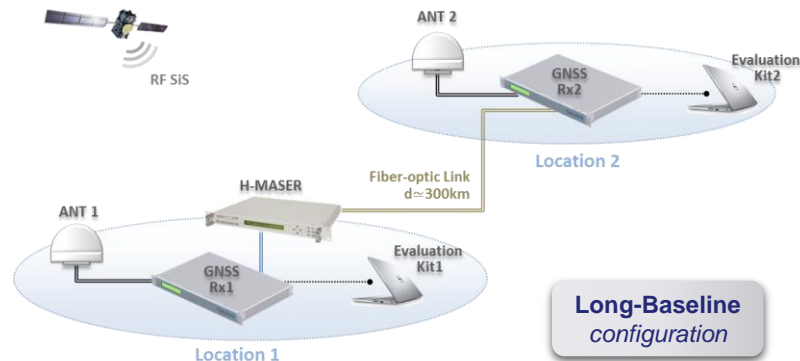
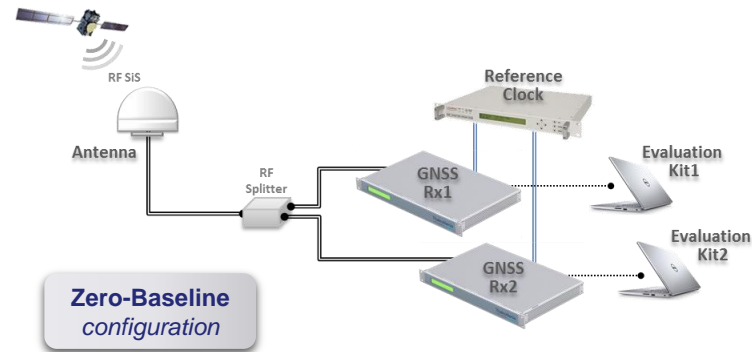
SRC PAS (Poland): **calibration** and **time transfer performance** verification in real environment ("Zero", "Short" or "Long" baseline tests).

3.

TAS-I & EC Joint Research Centre - JRC (Italy): verification of platform **robustness** and ability to withstand **Jamming** or **Spoofing** threats.

4.

Italian National Metrology Institute - INRIM (Italy): GIANO performance **benchmarking** against COTS multi-GNSS calibrated timing receivers and **UTC validation** at user level.



GIANO VALIDATION /// STANDARDIZATION & CERTIFICATION



No unique applicable **standard** to GNSS timing receivers.

Existing standards are more related to **data format and I/F**:

- Standards applicable to data format of high-end receivers, such as the **CGGTTS** format (BIPM).
- Ubiquitous standard used for timing (PPP) i.e. **RINEX**.
- Receivers used in critical infrastructures generally outputs time coded data in **IRIG-B** format, with variations for the power grid operators conforming to the old **IEEE C37.118** Standard (recently superseded by **IEEE Std C37.118.1** and **IEEE Std C37.118.2**).
- Financial transactions conform to recent **MIFID-II** directive.



Timing services **certification** is the **added-value** making service more appealing to users.

An **approach to Certification** of a GNSS timing receiver could consider as a minimum:

- Receiver **overall performances assessment** under operating conditions (e.g. jamming, spoofing, etc.).
- **Calibration** by a **certified laboratory** (and possibly auto-calibration of the receiver during operation).
- **Remote monitoring** of overall performance may be required by specific applications.



Thanks For Your Attention!

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